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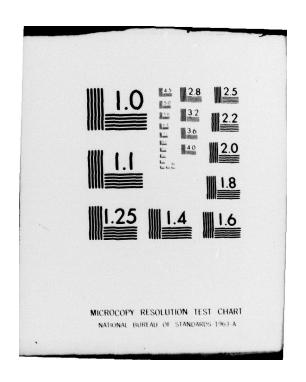
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COMMUNICATION APPLICATION OF ADAPTIVE ARRAYS

R.T. Compton, Jr.

The Ohio State University



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The Ohio State University

ElectroScience Laboratory

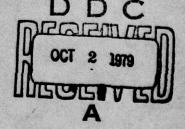
Department of Electrical Engineering Columbus, Ohio 43212

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June 1979

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Naval Air Systems Command Washington, D.C. 20361

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INTRODUCTION

This report describes progress under NASC Contract NO0019-79-C-0291 during the first quarterly period. There are three areas of work under this contract. The first involves studies on weight jitter and dynamic range for the improved LMS loop. The second is a continuation of research on a reference signal generation technique for FSK signals. The third area involves the preparation of a monograph on adaptive arrays.

II. PROGRESS

A. The Improved LMS Loop

Under the previous contract, a modified form of the LMS loop was found that solves the problem of time constant spread [1]. This new loop includes an averaging operation, originally defined as a finite time average. However, a finite time average is inconvenient to implement, and it would be preferable to use a simple lowpass filter instead.

During this quarter, studies and computer simulations have been done on the modified loop using a simple RC lowpass filter instead of the finite time average. The results show that this change can be made without substantially changing the performance of the system. With the lowpass filter in the loop, the differential equations for the weights are 2nd order, instead of 1st order as with the finite time average. Each weight transient includes two exponential terms, one due to each pole of the differential equation. We find that as the signal power is varied, one pole has a fixed position in the complex frequency plane, and the other moves. The stationary pole yields the desired fixed time constant term in the weight response. The moving pole contributes a term whose time constant depends on signal power, but the amplitude of this term is extremely small compared to that of the fixed pole. As a result, this term contributes only negligibly to the weight transients. The weight transients thus have the desired behavior with the RC filter.

Work on the modified LMS loop is continuing with studies on weight jitter.

B. Reference Signal Generation with FSK Signals

Studies on the use of FSK signals with adaptive arrays have been continued. Recent work involves the acquisition behavior of the adaptive array with a reference signal generation loop. The FSK signal is assumed to be from a first-order Markov source with known transition probabilities. This assumption allows each bit to be predicted from the last bit, with a better-than-average probability of success. The array output is processed in a loop, as shown in Fig. 1, to produce the reference signal. In this loop, during each bit interval, the oscillator is keyed so that the predicted frequency of the desired signal is shifted to the center of the bandpass filter. The second mixer then shifts the filter output signal

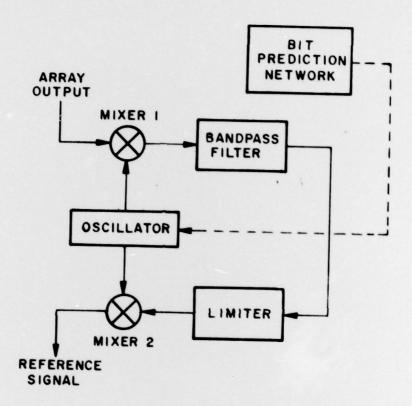


Fig. 1. The FSK Reference Signal Loop.

back to the original frequency where it becomes the reference signal. The limiter controls the level of the reference signal.

Computer simulations are being done for a two-element LMS array combined with this reference signal processing loop. The input to the array includes an FSK desired signal, interference, and thermal noise. Most simulations to date have assumed a large CW interference signal directly on one of the two FSK frequencies. The program computes the reference signal transients, the weight transients, and the antenna patterns.

These simulations are being done, along with theoretical analyses, to study the relationship between the reference loop parameters and the array lockup characteristics. The effects of prediction probability, filter characteristics, spurious frequencies (filter leak-through and mixer products) and limiter characteristics are being evaluated.

C. Adaptive Array Monograph

An introductory chapter on adaptive array feedback algorithms is currently being written. This chapter presents the feedback algorithms of Shor, Widrow, Applebaum, Griffiths and Frost in a unified manner, and also discusses methods for overcoming eigenvalue spread--Sample Matrix Inversion, Baird's technique, the improved LMS loop, and schemes related to a Gram-Schmidt orthogonalization procedure. A discussion of several other approaches, such as random search, phase-only control, and power optimization will also be included.

REFERENCE

[1] R.T. Compton, Jr., "An Improved Feedback Loop for Adaptive Arrays," Report 710929-3, July 1978, The Ohio State University Electro-Science Laboratory, Department of Electrical Engineering; prepared under Contract NO0019-78-C-0131 for Naval Air Systems Command.